

Synchronization, detection and equalization for Continuous Phase Modulation over doubly-selective channels

Romain Chayot

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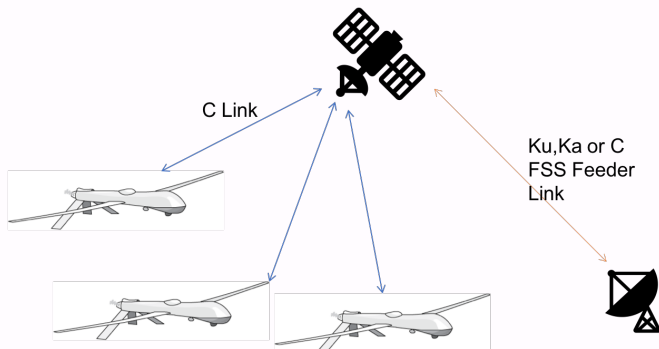
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Context

► Command & Non Payload Communication Link by Satellite



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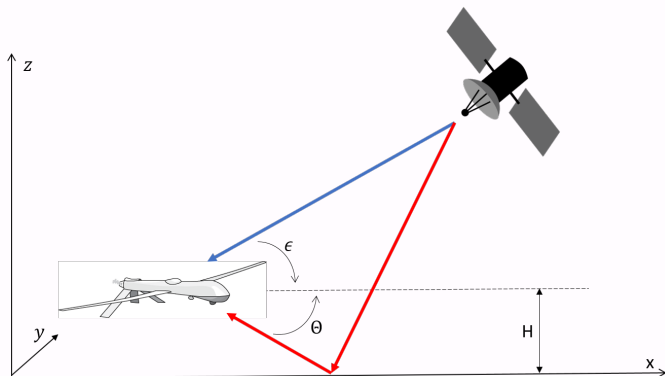
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Constraints

- ▶ Non linearities introduced by embedded amplifiers
- ▶ Multi-path channels



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Choice of Continuous Phase Modulation

- ▶ Non-linear modulation;
- ▶ Constant complex envelope;
- ▶ Robustness to non-linearities introduced by amplifiers (no need of IBO);
- ▶ Good spectral occupancy;
- ▶ already in use in satellite communication standards (such as DVB-RCS2) or for tactical communications.

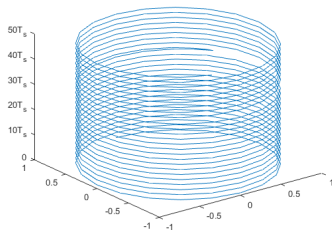


Figure: CPM signal in a polar plan (Quaternary CPM, $L=2$, $h=1/4$, RC pulse shape

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Main contributions

- ▶ A new Minimum Mean Square Error - Frequency Domain Equalizer for CPM transmissions over frequency-selective channels
 - ▶ Has the same performance as others State of the Art Equalizers
 - ▶ But with a significantly lower computational complexity
 - ▶ Has been extended to a low-complexity "approximate" equalizer in case of doubly-selective channels

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- ▶ A new Minimum Mean Square Error - Frequency Domain Equalizer for CPM transmissions over frequency-selective channels
 - ▶ Has the same performance as others State of the Art Equalizers
 - ▶ But with a significantly lower computational complexity
 - ▶ Has been extended to a low-complexity "approximate" equalizer in case of doubly-selective channels
- ▶ Joint Carrier Frequency Offset and channel estimation
 - ▶ Compatible with the equalization schemes for CPM
 - ▶ Reaches asymptotically the Cramér Rao Bound
 - ▶ can use a parametric model (case of the aeronautical channel)
 - ▶ Has been extended to Time-Varying channels

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BICM for CPM

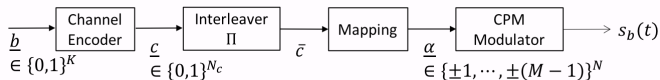


Figure: BICM for CPM signals

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Complex envelope

Complex envelope $s_b(t)$ associated with the transmitted CPM signal:

$$s_b(t) = \sqrt{\frac{2E_s}{T_s}} \exp(j\theta(t, \underline{\alpha})) \quad (1)$$

$$\text{where } \theta(t, \underline{\alpha}) = 2\pi h \sum_{i=0}^{N-1} \alpha_i q(t - iT_s)$$

$$\text{and } q(t) = \begin{cases} \int_0^t g(\tau) d\tau, & t \leq LT_s \\ 1/2, & t > LT_s \end{cases}$$

E_s is the symbol energy, T_s is the symbol period, $\theta(t, \underline{\alpha})$ is the information phase, $g(t)$ is the pulse response, h is the modulation index and L is the CPM memory.

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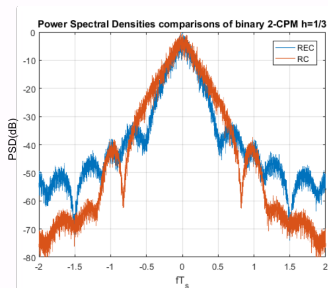
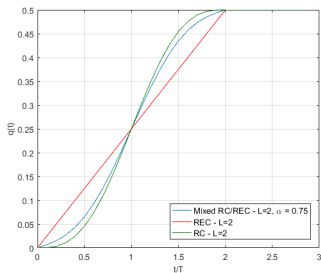
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CPM parameters

- ▶ Pulse shapes
 - ▶ Gaussian Minimum Shift Keying (*GMSK*)
 - ▶ Rectangular (*REC*)
 - ▶ Raised Cosine (*RC*)
 - ▶ ...
- ▶ with different properties on the CPM signal



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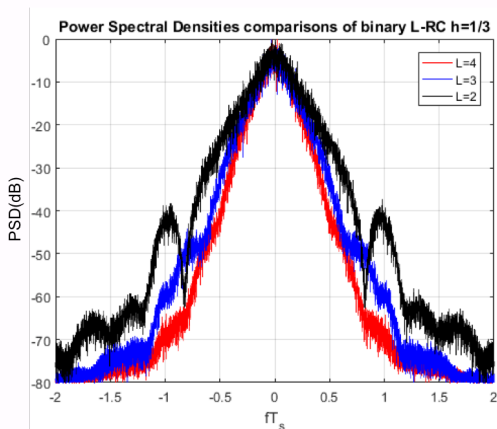
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CPM parameters

▶ CPM Memory L



▶ When L increases

- ▶ Reduces the spectrum occupancy
- ▶ Increases the receiver complexity

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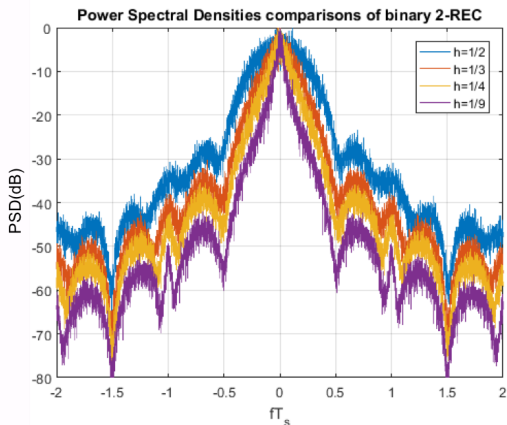
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CPM parameters

▶ Modulation index h

- ▶ h is generally a rational number $h = \frac{k}{p}$ smaller than 1
- ▶ p has an influence on the number of state of the CPM trellis
- ▶ When h decreases, the bandwidth occupancy is smaller ... but the Euclidean distance is smaller too



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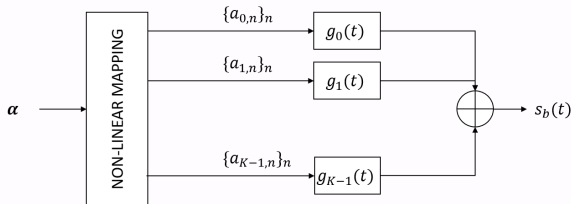
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Laurent Decomposition

- ▶ A binary CPM with non-integer modulation index can be represented as a sum of linear PAM [Lau86]:

$$s_b(t) = \sum_{k=0}^{K-1} \sum_{n=0}^{N-1} a_{k,n} g_k(t - nT_s) \quad (2)$$

- ▶ K is the number of Laurent Pulses
- ▶ The non-linearities is within the pseudo-symbols $\{a_{k,n}\}$
- ▶ The PAM decomposition has been extended to M -ary CPMs and also to integer indices schemes



Features of PAM Decomposition

- ▶ Most of the energy is within the first "M-1" components

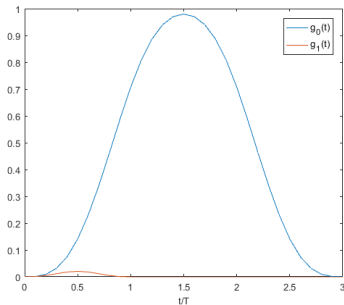


Figure: Example: Binary CPM, Averaged REC/RC ($\alpha = 0.75$), $L = 2$ and $h = 1/2$)

- ▶ Can be used to design low-complexity detector

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CPM Detector (AWGN Channel)

- ▶ Received signal: $r(t) = s_b(t) + w(t)$

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CPM Detector (AWGN Channel)

- ▶ Received signal: $r(t) = s_b(t) + w(t)$
- ▶ MAP Detector using the BCJR algorithm [CB05]

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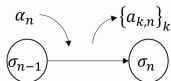
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- ▶ Received signal: $r(t) = s_b(t) + w(t)$
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- ▶ Capitalizes on the PAM Decomposition



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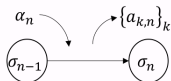
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- ▶ Capitalizes on the PAM Decomposition



- ▶ Sufficient statistics:

$$r_{k,n} = \int_0^{(L+1)T_s} r(t + nT_s) g_k^*(-t) dt \quad (3)$$

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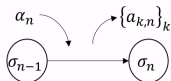
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- ▶ Branch metric:

$$\mathcal{G}_n(\sigma_{n-1}, \sigma_n) \propto \exp \left\{ \frac{2}{N_0} \Re \left\{ \sum_{k=0}^{K-1} r_{k,n} a_{k,n}^* \right\} \right\} \pi(\alpha_n) \quad (4)$$

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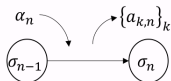
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- ▶ Low Complexity Design by taking $K = M - 1$

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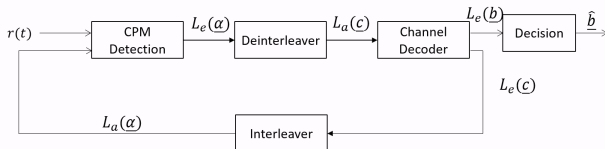
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► Iterative receiver



► Non-iterative receiver

- No iteration between the CPM detection and the outer channel decoder
- Can result in a non-negligible loss of performance
- May be optimal in case of "non-recursive" CPM or in case of "pragmatic CPM" (precoder)

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Contributions

- ▶ Equivalences and differences between State of the Art MMSE-FDE for CPM over frequency-selective channels
- ▶ Design of a low-complexity MMSE-FDE for CPM over frequency-selective channels
- ▶ Extension to CPM transmissions over doubly selective channels

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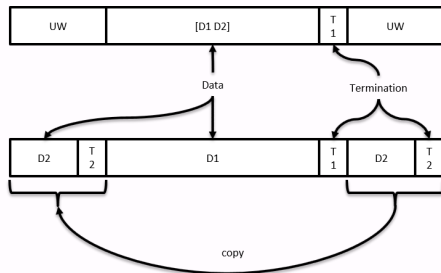
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System Model

- ▶ Received signal is the linear convolution between the transmitted signal and the channel (filtered by a LPF)
- ▶ Circularization of the signal by the insertion of a CP or an UW
 - ▶ Similar to linear modulation up to termination symbols to ensure the phase continuity



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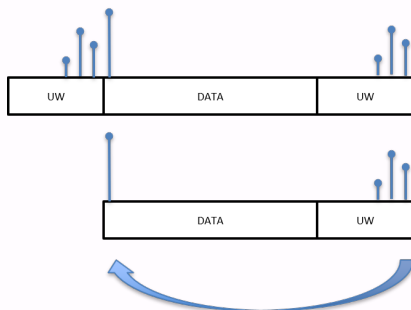
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System Model

- Circular convolution between the channel and the transmitted over-sampled complex envelop

$$r[n] = \sum_m h[m]s[\text{mod}(n - m, kN)] \quad (5)$$



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MMSE-FDE for CPM over TIV channels

- ▶ Optimal receiver
 - ▶ Joint channel equalization and data detection
 - ▶ Prohibitive complexity
 - ▶ Separation of channel equalization and data detection

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- ▶ Optimal receiver
 - ▶ Joint channel equalization and data detection
 - ▶ Prohibitive complexity
 - ▶ Separation of channel equalization and data detection
- ▶ Frequency Domain Equalization (FDE)
 - ▶ Complexity does not depend on the channel delay span
 - ▶ Can achieve low complexity structure (linear modulation)

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 - ▶ Complexity does not depend on the channel delay span
 - ▶ Can achieve low complexity structure (linear modulation)
- ▶ State of the Art MMSE-FDE
 - ▶ Channel and Laurent Pulses Equalizer (Pancaldi)
 - ▶ Channel Equalizer (Van Thillo)
 - ▶ Equivalence

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- ▶ Optimal receiver
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 - ▶ Complexity does not depend on the channel delay span
 - ▶ Can achieve low complexity structure (linear modulation)
- ▶ State of the Art MMSE-FDE
 - ▶ Channel and Laurent Pulses Equalizer (Pancaldi)
 - ▶ Channel Equalizer (Van Thillo)
 - ▶ Equivalence
- ▶ Contribution
 - ▶ A new exact low complexity MMSE-FDE
 - ▶ Complexity in $O(N\log(N))$
 - ▶ Same performance as the others equalizers

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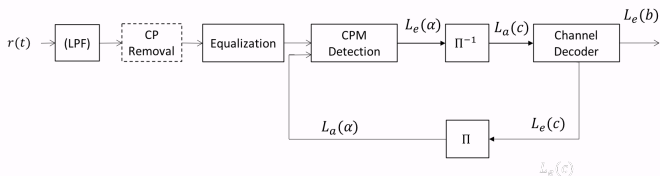
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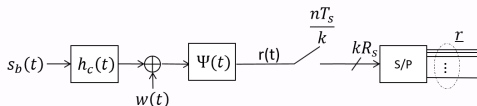
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Channel and Laurent Pulses Equalizer (1/2)

- ▶ Fractionally-spaced representation of the signal



- ▶ $\Psi(t)$ ideal LPF
- ▶ Received signal in the FD:

$$\underline{R} = \underbrace{\underline{HL}}_{\triangleq \underline{M}} \underline{B}_{2N} + \underline{W} = \underline{MB}_{2N} + \underline{W} \quad (6)$$

- ▶ Equalizer given by $\underline{D}_{LE} = \underline{JM}^H [\underline{M\Phi M}^H + \sigma_n^2 I_{2N}]^{-1}$:

$$\underline{\hat{B}} = \underline{JM}^H [\underline{M\Phi M}^H + \sigma_n^2 I_{2N}]^{-1} \underline{R} \quad (7)$$

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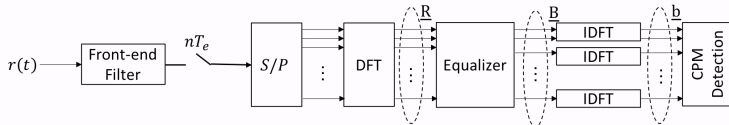
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Channel and Laurent Pulses Equalizer (2/2)

- ▶ Interest:
 - ▶ If only one LP is considered, similar to [TS05]
 - ▶ Similar to a Fractionally Spaced Equalizer (taking into account the correlation of the pseudo-symbols)
- ▶ Main issues:
 - ▶ Full auto-correlation matrix of the pseudo-symbols vectors $\underline{\Phi}$ to inverse
 - ▶ Requires a non-conventional CPM detector



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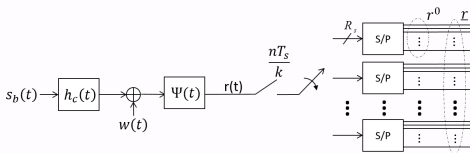
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Channel Equalizer (1/2)

- Polyphase representation of the signal



- Received signal in the FD:

$$\underline{R}_p = \underline{H}_p \underbrace{\underline{L}_p \underline{B}}_{\triangleq \underline{S}_p} + \underline{W}_p = \underline{H}_p \underline{S}_p + \underline{W}_p \quad (8)$$

- Equalizer given by

$$\underline{G} = \underline{R}_{SS,p} \underline{H}^H [\underline{H} \underline{R}_{SS,p} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1}$$

$$\hat{\underline{S}}_p = \underline{R}_{SS,p} \underline{H}^H [\underline{H} \underline{R}_{SS,p} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}_p \quad (9)$$

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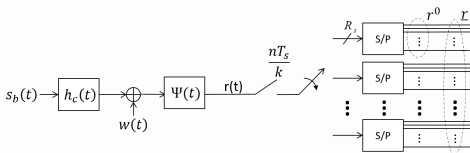
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- Polyphase representation of the signal



- Received signal in the FD:

$$\underline{R}_p = \underline{H}_p \underbrace{\underline{L}_p \underline{B}}_{\triangleq \underline{S}_p} + \underline{W}_p = \underline{H}_p \underline{S}_p + \underline{W}_p \quad (8)$$

- Equalizer given by

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$$\hat{\underline{S}}_p = \underline{R}_{SS,p} \underline{H}^H [\underline{H} \underline{R}_{SS,p} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}_p \quad (9)$$

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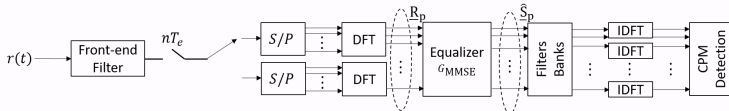
Channel Equalizer (2/2)

- ▶ $\underline{R}_{SS,p}$ non diagonal matrix
 - ▶ Due to the polyphase representation, its Time-Domain counterpart is NOT a circulant matrix:

$$\underline{r}_{SS,p} = \mathbb{E}[\underline{s}_p \underline{s}_p^H]$$

$$= \begin{bmatrix} r_{SS}(0) & r_{SS}^*(2) & r_{SS}^*(4) & \dots & r_{SS}^*(2N-2) & r_{SS}^*(1) & r_{SS}^*(3) & \dots & r_{SS}^*(2N-1) \\ r_{SS}(2) & r_{SS}(0) & r_{SS}^*(2) & \dots & r_{SS}^*(2N-4) & r_{SS}(3) & r_{SS}^*(1) & \dots & r_{SS}^*(2N-3) \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ r_{SS}(0) & r_{SS}(2N-2) & r_{SS}(2N-4) & \dots & r_{SS}(2) & r_{SS}(2N-1) & r_{SS}(2N-3) & \dots & r_{SS}(1) \\ r_{SS}(2) & r_{SS}(0) & r_{SS}(2N-2) & \dots & r_{SS}(4) & r_{SS}(3) & r_{SS}(2N-1) & \dots & r_{SS}(3) \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

- ▶ Conventional CPM Detector



Synchronization, detection and equalization for Continuous Phase Modulation over doubly-selective channels

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Equivalence

- ▶ Both MMSE-FDE (same sampling rate...)
- ▶ Should have the same performance
- ▶ Channel Equalizer: $\underline{\tilde{S}} = \underline{GR}$
- ▶ Channel and LP Equalizer: $\underline{\hat{B}} = \underline{D}_{LE} \underline{R}$
- ▶ Link between them: $\underline{G}_{MMSE} = \underline{L}_p \underline{D}_{LE}$
- ▶ Therefore $\underline{\tilde{S}} = \underline{L}_p \underline{\hat{B}}$
- ▶ Strictly equivalent up to a proper linear post-processing

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Limitation of the previous equalizers

- ▶ Both uses the circularization of the channel:
 - ▶ Channel matrix diagonal in the FD
 - ▶ But time-averaged auto-correlation matrix NOT diagonal
 - ▶ Still have an important computational complexity
- ▶ Does NOT exploit the circularization of the signal

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A new MMSE-FDE

- ▶ Also a MMSE - Frequency Domain Equalizer
- ▶ We use the Fractionally-Spaced Representation
- ▶ We achieve the same performance than the previous MMSE-FDEs
 - ▶ No approximation is made
- ▶ ... but with a significantly lower complexity
 - ▶ "One-tap" MMSE-FDE
 - ▶ by exploiting the circular properties of the signal

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Circularization of the signal

- ▶ Equivalence between the circular convolution and the linear convolution
- ▶ Over a finite-time observation, equivalence between this circular convolution and a linear convolution of \underline{h} and a periodic version of \underline{s}
- ▶ By considering this periodic version of \underline{s} , the time-averaged auto-correlation function of \underline{s} is periodic

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- ▶ Equivalence between the circular convolution and the linear convolution
- ▶ Over a finite-time observation, equivalence between this circular convolution and a linear convolution of \underline{h} and a **periodic** version of \underline{s}
- ▶ By considering this periodic version of \underline{s} , the time-averaged auto-correlation function of \underline{s} is **periodic**

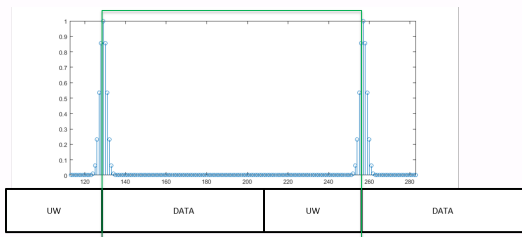


Figure: Periodization of the time-averaged auto-correlation function

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Derivation of the equalizer

- ▶ Use the FS representation of the signal as [PV06]

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Derivation of the equalizer

- ▶ Use the FS representation of the signal as [PV06]
- ▶ Considers only the channel contribution as [VT+09]

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Derivation of the equalizer

- ▶ Use the FS representation of the signal as [PV06]
- ▶ Considers only the channel contribution as [VT+09]
- ▶ Received signal in the FD: $\underline{R} = \underline{H}\underline{S} + \underline{W}$
- ▶ Equalizer given by:

$$\underline{J}_{\text{MMSE}} = \underline{R}_{\text{SS}} \underline{H}^H (\underline{H} \underline{R}_{\text{SS}} \underline{H}^H + \sigma_n^2 \underline{I}_{n=KN})^{-1} \quad (10)$$

Derivation of the equalizer

- ▶ Use the FS representation of the signal as [PV06]
- ▶ Considers only the channel contribution as [VT+09]
- ▶ Received signal in the FD: $\underline{R} = \underline{H}\underline{S} + \underline{W}$
- ▶ Equalizer given by:

$$\underline{J}_{\text{MMSE}} = \underline{R}_{\text{SS}} \underline{H}^H (\underline{H} \underline{R}_{\text{SS}} \underline{H}^H + \sigma_n^2 \underline{I}_{n_{kN}})^{-1} \quad (10)$$

Derivation the equalizer

- ▶ $r_{=ss}$ is the time-averaged discrete auto-correlation function of the over-sampled complex envelope of the transmitted CPM signal

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Derivation the equalizer

- ▶ $\underline{r}_{\text{SS}}$ is the time-averaged discrete auto-correlation function of the over-sampled complex envelope of the transmitted CPM signal

- ▶ also periodic
- ▶ $r_{\text{SS}}^*(l) = r_{\text{SS}}(-l) = r_{\text{SS}}(kN - l)$
- ▶ $\underline{r}_{\text{SS}}$ is circulant
- ▶ $\underline{R}_{\text{SS}}$ is diagonal, by DFT properties (as \underline{H})

$$\underline{r}_{\text{SS}} = \begin{bmatrix} r_{\text{SS}}(0) & r_{\text{SS}}^*(1) & r_{\text{SS}}^*(2) & \dots & r_{\text{SS}}^*(kN - 1) \\ r_{\text{SS}}(1) & r_{\text{SS}}(0) & r_{\text{SS}}^*(1) & \dots & r_{\text{SS}}^*(kN - 2) \\ r_{\text{SS}}(2) & r_{\text{SS}}(1) & r_{\text{SS}}(0) & \dots & r_{\text{SS}}^*(kN - 3) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_{\text{SS}}(kN - 1) & r_{\text{SS}}(kN - 2) & r_{\text{SS}}(kN - 3) & \dots & r_{\text{SS}}(0) \end{bmatrix} \quad (11)$$

$$= \begin{bmatrix} r_{\text{SS}}(0) & r_{\text{SS}}(kN - 1) & r_{\text{SS}}(kN - 2) & \dots & r_{\text{SS}}(1) \\ r_{\text{SS}}(1) & r_{\text{SS}}(0) & r_{\text{SS}}(kN - 1) & \dots & r_{\text{SS}}(2) \\ r_{\text{SS}}(2) & r_{\text{SS}}(1) & r_{\text{SS}}(0) & \dots & r_{\text{SS}}(3) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_{\text{SS}}(kN - 1) & r_{\text{SS}}(kN - 2) & r_{\text{SS}}(kN - 3) & \dots & r_{\text{SS}}(0) \end{bmatrix} \quad (12)$$

Derivation the equalizer

- ▶ \underline{r}_{SS} is the time-averaged discrete auto-correlation function of the over-sampled complex envelope of the transmitted CPM signal
 - ▶ also periodic
 - ▶ $r_{SS}^*(l) = r_{SS}(-l) = r_{SS}(kN - l)$
 - ▶ \underline{r}_{SS} is circulant
 - ▶ \underline{R}_{SS} is diagonal, by DFT properties (as \underline{H})

$$\underline{r}_{SS} = \begin{bmatrix} r_{SS}(0) & r_{SS}^*(1) & r_{SS}^*(2) & \dots & r_{SS}^*(kN-1) \\ r_{SS}(1) & r_{SS}(0) & r_{SS}^*(1) & \dots & r_{SS}^*(kN-2) \\ r_{SS}(2) & r_{SS}(1) & r_{SS}(0) & \dots & r_{SS}^*(kN-3) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_{SS}(kN-1) & r_{SS}(kN-2) & r_{SS}(kN-3) & \dots & r_{SS}(0) \end{bmatrix} \quad (11)$$

$$= \begin{bmatrix} r_{SS}(0) & r_{SS}(kN-1) & r_{SS}(kN-2) & \dots & r_{SS}(1) \\ r_{SS}(1) & r_{SS}(0) & r_{SS}(kN-1) & \dots & r_{SS}(2) \\ r_{SS}(2) & r_{SS}(1) & r_{SS}(0) & \dots & r_{SS}(3) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_{SS}(kN-1) & r_{SS}(kN-2) & r_{SS}(kN-3) & \dots & r_{SS}(0) \end{bmatrix} \quad (12)$$

Structure of the equalizer

- ▶ \mathbf{J}_{MMSE} is a diagonal matrix
- ▶ "One-tap" MMSE-FDE:

$$J[l] = \frac{R_{SS}[l]H^*[l]}{R_{SS}[l]|H[l]|^2 + \sigma_n^2} \quad (13)$$

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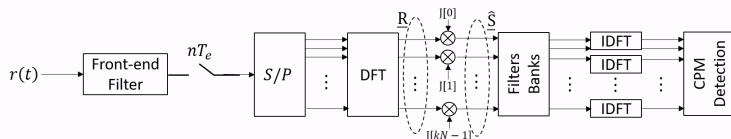
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Structure of the equalizer

- ▶ \mathbf{J}_{MMSE} is a diagonal matrix
- ▶ "One-tap" MMSE-FDE:

$$\mathbf{J}[l] = \frac{R_{SS}[l]H^*[l]}{R_{SS}[l]|H[l]|^2 + \sigma_n^2} \quad (13)$$

- ▶ Use of a conventional CPM Detector
- ▶ Has a low-complexity structure *without* any approximation



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Difference with the Channel MMSE-FDE [VT+09]

- ▶ Difference in the representation of the received signal
- ▶ Using the polyphase representation, the time-domain auto-correlation matrix of the over-sampled complex envelope does not have anymore a circular structure

$$\underline{\underline{r}}_{\text{ss},p} \quad (14)$$

$$= \mathbb{E}[\underline{s}_p \underline{s}_p^H] \quad (15)$$

$$= \begin{bmatrix} r_{\text{ss}}(0) & r_{\text{ss}}^*(2) & r_{\text{ss}}^*(4) & \dots & r_{\text{ss}}^*(2N-2) & r_{\text{ss}}^*(1) & r_{\text{ss}}^*(3) & \dots & r_{\text{ss}}^*(2N-1) \\ r_{\text{ss}}(2) & r_{\text{ss}}(0) & r_{\text{ss}}^*(2) & \dots & r_{\text{ss}}^*(2N-4) & r_{\text{ss}}(3) & r_{\text{ss}}(1) & \dots & r_{\text{ss}}^*(2N-3) \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix} \quad (16)$$

- ▶ Its FD counterpart is therefore not diagonal
- ▶ Also, the Channel matrix in the FD ($\underline{\underline{H}}_p$) is not a diagonal in the Polyphase Rep.

Summary and Computational complexity comparison

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Notation	Reference	Equalizer	Signal Rep.
LD-FS-MMSE-FDE	[PV06]	$\hat{\underline{B}} = \underline{J} \underline{M}^H [\underline{M} \underline{\Phi} \underline{M}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}$	FS
PP-MMSE-FDE	[VT+09]	$\hat{\underline{S}}_p = \underline{R}_{SS,p} \underline{H}^H [\underline{H} \underline{R}_{SS,p} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}_p$	Polyphase
LD-PP-MMSE-FDE	[Cha+17]	$\hat{\underline{B}} = \underline{R}_{BB} \underline{P}^H [\underline{P} \underline{R}_{BB} \underline{P}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}_p$	Polyphase
FS-MMSE-FDE	[Cha+18]	$\hat{\underline{S}} = \underline{R}_{SS} \underline{H}^H [\underline{H} \underline{R}_{SS} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}$	FS

Receiver Type	FFTs and IFFTs	Equalizer Calc.	Equalization
Linear MMSE-TDE [PV06]	0	$+8N^3$	$+\mathcal{O}(PN^3)$
LD-FS-MMSE-FDE [PV06]	$2N \log(2N) + PN \log(N)$	$+8N^3$	$+\mathcal{O}(PN^3)$
PP-MMSE-FDE [VT+09]	$2N \log(N) + PN \log(N)$	$+8N^3$	$+\mathcal{O}(PN^3)$
Approx. PP-MMSE-FDE [VT+09]	$2N \log(N) + PN \log(N)$	$+\mathcal{O}(2N)$	$+\mathcal{O}(PN)$
FS-MMSE-FDE	$2N \log(2N) + PN \log(N)$	$+\mathcal{O}(2N)$	$+\mathcal{O}(PN)$

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Summary and Computational complexity comparison

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Notation	Reference	Equalizer	Signal Rep.
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PP-MMSE-FDE	[VT+09]	$\hat{\underline{S}}_p = \underline{R}_{SS,p} \underline{H}^H [\underline{H} \underline{R}_{SS,p} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}_p$	Polyphase
LD-PP-MMSE-FDE	[Cha+17]	$\hat{\underline{B}} = \underline{R}_{BB} \underline{P}^H [\underline{P} \underline{R}_{BB} \underline{P}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}_p$	Polyphase
FS-MMSE-FDE	[Cha+18]	$\hat{\underline{S}} = \underline{R}_{SS} \underline{H}^H [\underline{H} \underline{R}_{SS} \underline{H}^H + \sigma_n^2 \underline{I}_{2N}]^{-1} \underline{R}$	FS

Receiver Type	FFTs and IFFTs	Equalizer Calc.	Equalization
Linear MMSE-TDE [PV06]	0	$+8N^3$	$+\mathcal{O}(PN^3)$
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Simulation Results (1/2)

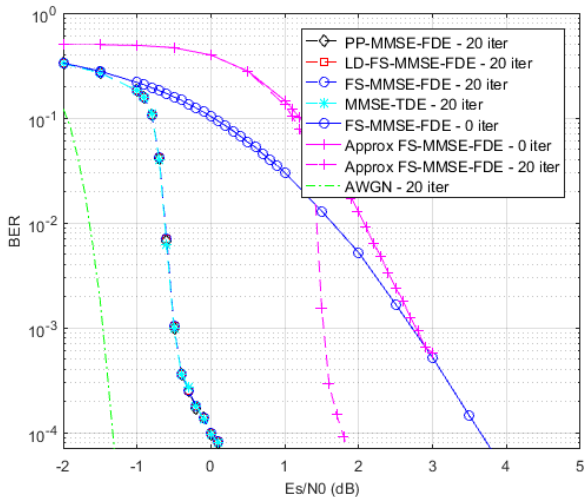


Figure: BER over an aeronautical channel

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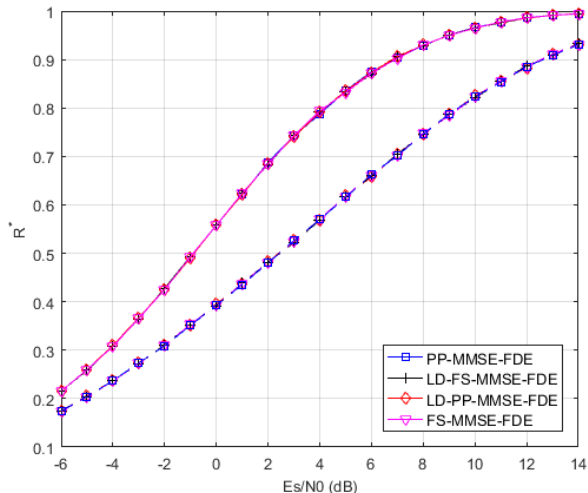


Figure: Maximum achievable coding rate for the different MMSE-FDE over a generic frequency-selective channel

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An extension to Time-Varying Channels: Motivation

- ▶ CPM transmission over Time-Variant (TV) channels

$$r[l] = r\left(\frac{lT}{k}\right) = \sum_m s[m]h[l; l-m] + w[l] \quad (17)$$

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$$r[l] = r\left(\frac{lT}{k}\right) = \sum_m s[m]h[l; l-m] + w[l] \quad (17)$$

- ▶ State of the Art [Dar+16]
 - ▶ MMSE Time-Domain Equalizer
 - ▶ Complexity growing with the channel span
 - ▶ Capitalizes on the Laurent Decomposition

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- ▶ State of the Art [Dar+16]
 - ▶ MMSE Time-Domain Equalizer
 - ▶ Complexity growing with the channel span
 - ▶ Capitalizes on the Laurent Decomposition
- ▶ Main Issue for MMSE-FDE
 - ▶ FD channel matrix is no more diagonal
 - ▶ Requires higher computation (inversion of full matrix)

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Band MMSE-FDE: Motivation

- ▶ Main idea: exploit the band structure of the channel matrix in the FD ([RBL06])

$$\underline{\underline{H}} \approx \underline{\underline{H}}_Q = \underline{\underline{B}}^{(Q)} \circ \underline{\underline{H}} \quad (18)$$

$\underline{\underline{B}}^{(Q)}$ matrix with 1's only on Q sub-diagonals
○ element-wise multiplication

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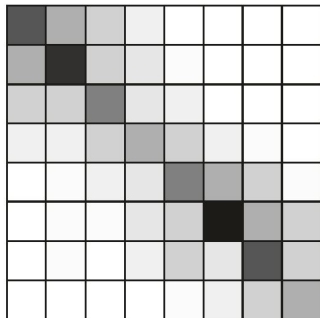


Figure: FD channel matrix from [RBL06]

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Band MMSE-FDE: Derivation & Procedure

- ▶ Linear block MMSE equalizer given by:

$$\mathbf{J}_{\text{MMSE},Q} = \mathbf{R}_{SS} \mathbf{H}^H (\mathbf{H} \mathbf{R}_{SS} \mathbf{H}^H + \sigma_n^2 \mathbf{I}_{2N})^{-1} \quad (19)$$

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- ▶ Capitalization on the band structure of $\mathbf{J}_{\text{MMSE},Q}$

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Band MMSE-FDE: Derivation & Procedure

- ▶ Linear block MMSE equalizer given by:

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- ▶ Capitalization on the band structure of $\underline{\underline{J}}_{\text{MMSE},Q}$

- ▶ Procedure:

- ▶ Compute the band matrix $\underline{\underline{K}} = \underline{\underline{H}} \underline{\underline{R}}_{SS} \underline{\underline{H}}^H + \sigma_n^2 \underline{\underline{I}}_{kN}$;
- ▶ Compute the LDL decomposition of $\underline{\underline{K}} = \underline{\underline{L}} \underline{\underline{D}} \underline{\underline{L}}^H$ where $\underline{\underline{L}}$ is a lower triangular matrix and $\underline{\underline{D}}$ a diagonal matrix following [RBL05] ;
- ▶ Solve the triangular system $\underline{\underline{L}} \underline{\underline{f}} = \underline{\underline{R}}$;
- ▶ Solve the diagonal system $\underline{\underline{D}} \underline{\underline{g}} = \underline{\underline{f}}$;
- ▶ Solve the triangular system $\underline{\underline{L}}^H \underline{\underline{d}} = \underline{\underline{g}}$;
- ▶ Solve the triangular system $\underline{\underline{L}}^H \underline{\underline{d}} = \underline{\underline{g}}$

Band MMSE-FDE: Derivation & Procedure

- ▶ Linear block MMSE equalizer given by:

$$\underline{\underline{\mathbf{J}}}_{\text{MMSE},Q} = \underline{\underline{\mathbf{R}}}_{SS} \underline{\underline{\mathbf{H}}}^H (\underline{\underline{\mathbf{H}}} \underline{\underline{\mathbf{R}}}_{SS} \underline{\underline{\mathbf{H}}}^H + \sigma_n^2 \underline{\underline{\mathbf{I}}}_{2N})^{-1} \quad (19)$$

- ▶ Capitalization on the band structure of $\underline{\underline{\mathbf{J}}}_{\text{MMSE},Q}$

- ▶ Procedure:

- ▶ Compute the band matrix $\underline{\underline{\mathbf{K}}} = \underline{\underline{\mathbf{H}}} \underline{\underline{\mathbf{R}}}_{SS} \underline{\underline{\mathbf{H}}}^H + \sigma_n^2 \underline{\underline{\mathbf{I}}}_{kN}$;
- ▶ Compute the LDL decomposition of $\underline{\underline{\mathbf{K}}} = \underline{\underline{\mathbf{L}}} \underline{\underline{\mathbf{D}}} \underline{\underline{\mathbf{L}}}^H$ where $\underline{\underline{\mathbf{L}}}$ is a lower triangular matrix and $\underline{\underline{\mathbf{D}}}$ a diagonal matrix following [RBL05] ;
- ▶ Solve the triangular system $\underline{\underline{\mathbf{L}}} \underline{\underline{\mathbf{f}}} = \underline{\underline{\mathbf{R}}}$;
- ▶ Solve the diagonal system $\underline{\underline{\mathbf{D}}} \underline{\underline{\mathbf{g}}} = \underline{\underline{\mathbf{f}}}$;
- ▶ Solve the triangular system $\underline{\underline{\mathbf{L}}}^H \underline{\underline{\mathbf{d}}} = \underline{\underline{\mathbf{g}}}$;
- ▶ Solve the triangular system $\underline{\underline{\mathbf{L}}} \underline{\underline{\mathbf{d}}} = \underline{\underline{\mathbf{g}}}$

- ▶ Computational complexity: $O(kN(2Q^2 + Q + \log(kN)))$

Simulation Results (1/3)

- ▶ "En Route" Scenario:
 - ▶ Aeronautical channel by satellite
 - ▶ C Band
 - ▶ Power ratio between the two paths: $C/M = 5dB$
 - ▶ Doppler Spread of 500Hz

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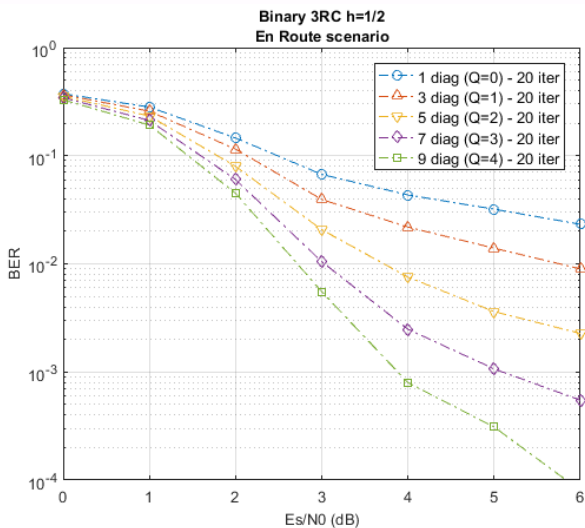


Figure: Influence of the parameter Q

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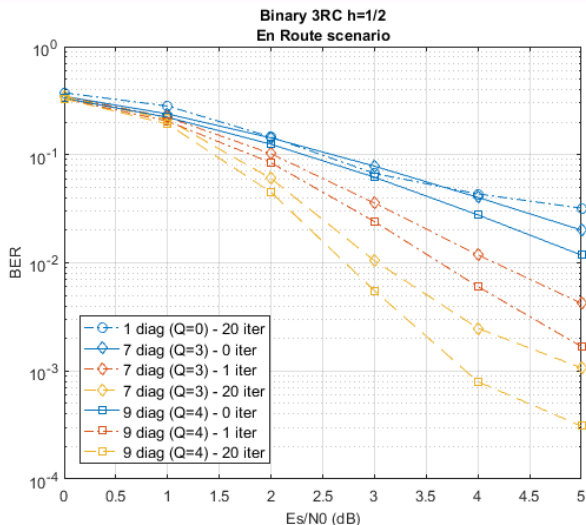


Figure: Influence of the parameter Q and of the number of iteration

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Motivation

- ▶ Previous work -> perfect synchronization and perfect channel knowledge
- ▶ CFO, phase and timing recovery
 - ▶ most of those methods for CPM transmission over AWGN channels
 - ▶ CRB derived in case of AWGN channels [HP13]
- ▶ Case of interest: transmission over TIV and TV channels

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 - ▶ Case of TIV channels
 - ▶ Case of TV channels (using BEM)
- ▶ Joint Carrier Frequency Offset and Channel Estimation
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 - ▶ Case of TV channels
 - ▶ Derivation of the Cramér Rao Bound

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System Model

- ▶ Received signal:

$$\begin{bmatrix} r[0] \\ r[1] \\ \vdots \\ r[kJ-1] \end{bmatrix} = \begin{bmatrix} s[0] & s[-1] & \dots & s[-L_h+1] \\ s[1] & s[0] & \dots & \dots \\ s[L_h-1] & \dots & s[1] & s[0] \\ \vdots & \vdots & \vdots & \vdots \\ s[kJ-1] & \dots & s[kJ-L_h+1] & s[kJ-L_h] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \\ \vdots \\ h[L_h-1] \end{bmatrix} + \underline{\mathbf{w}} \quad (20)$$

$$= \underline{\mathbf{sh}} + \underline{\mathbf{w}} \quad (21)$$

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$$\begin{bmatrix} r[0] \\ r[1] \\ \vdots \\ r[kJ-1] \end{bmatrix} = \begin{bmatrix} s[0] & s[-1] & \dots & s[-L_h+1] \\ s[1] & s[0] & \dots & \dots \\ s[L_h-1] & \dots & s[1] & s[0] \\ \vdots & \vdots & \vdots & \vdots \\ s[kJ-1] & \dots & s[kJ-L_h+1] & s[kJ-L_h] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \\ \vdots \\ h[L_h-1] \end{bmatrix} + \underline{\mathbf{w}} \quad (20)$$

$$= \underline{\mathbf{sh}} + \underline{\mathbf{w}} \quad (21)$$

- ▶ Difference with linear modulations:
 - ▶ We do not estimate a discrete equivalent channel (at baud rate)
 - ▶ We estimate an over-sampled channel filtered by a LPF at the receiver

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Channel to estimate

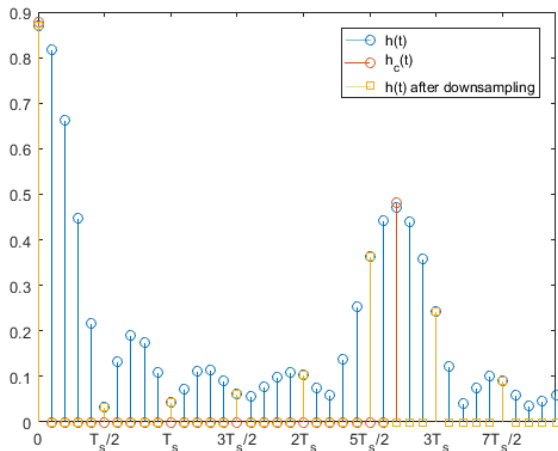


Figure: Finite impulse responses of $h_c(t)$ and $h(t)$

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- ▶ Least Squares Channel estimate:

$$\hat{\underline{h}}_{LS} = (\underline{\underline{s}}^H \underline{\underline{s}})^{-1} \underline{\underline{s}}^H \underline{r} \quad (22)$$

- ▶ Works at kR_s ($k \geq 2$)
- ▶ Can be improved by using an *a priori* knowledge of the delays (aeronautical channel by satellite)
- ▶ Can be extended to TV Channels using Basis Expansion Models (*BEM*)

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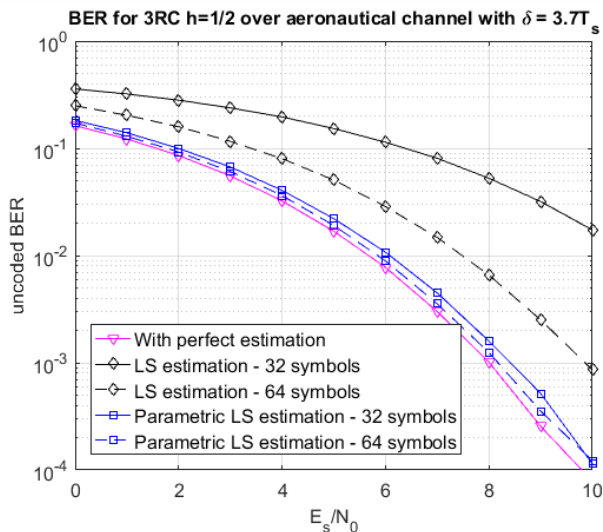


Figure: Unencoded BER over the aeronautical channel with channel estimation

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- ▶ Introduction of a Carrier Frequency Offset:

$$\underline{r} = \underline{\underline{\Gamma}}(f)\underline{sh} + \underline{w} \quad (23)$$

with

$$\underline{\underline{\Gamma}}(f) = \text{diag}\{1, e^{j2\pi f T_e}, e^{j2\pi f 2T_e}, \dots, e^{j2\pi f (kJ-1)T_e}\}$$

$$\underline{s} = \begin{bmatrix} s[0] & 0 & \dots & 0 \\ s[1] & s[0] & 0 & \vdots \\ s[L_h - 1] & \dots & s[1] & s[0] \\ \ddots & \ddots & \ddots & \ddots \\ s[kJ - 1] & \dots & s[kJ - L_h + 1] & s[kJ - L_h] \end{bmatrix}$$

$$\underline{h} = \begin{bmatrix} h[0] & h[1] & \dots & \dots & h[L_h - 1] \end{bmatrix}^T$$

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with

$$\underline{\Gamma}(f) = \text{diag}\{1, e^{j2\pi f T_e}, e^{j2\pi f 2T_e}, \dots, e^{j2\pi f (kJ-1)T_e}\}$$

$$\underline{s} = \begin{bmatrix} s[0] & 0 & \dots & 0 \\ s[1] & s[0] & 0 & \vdots \\ s[L_h - 1] & \dots & s[1] & s[0] \\ \ddots & \ddots & \ddots & \ddots \\ s[kJ - 1] & \dots & s[kJ - L_h + 1] & s[kJ - L_h] \end{bmatrix}$$

$$\underline{h} = [h[0] \quad h[1] \quad \dots \quad \dots \quad h[L_h - 1]]^T$$

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Joint ML Estimation of \underline{h} and the CFO f

- ▶ [MM00] for linear modulations
- ▶ Log-likelihood function for the parameters \underline{h} and f is:

$$\Delta(\underline{\tilde{h}}, \tilde{f}) = -\frac{1}{\sigma_n^2} [\underline{r} - \underline{\Gamma}(\tilde{f})\underline{s}\underline{\tilde{h}}]^H [\underline{r} - \underline{\Gamma}(\tilde{f})\underline{s}\underline{\tilde{h}}] \quad (24)$$

- ▶ Maximize Δ over $\underline{\tilde{h}}$ and \tilde{f}
- ▶ Estimate of \underline{h} for a given \tilde{f} is

$$\underline{\hat{h}}(\tilde{f}) = (\underline{s}^H \underline{s})^{-1} \underline{s}^H \underline{\Gamma}^H(\tilde{f}) \underline{r} \quad (25)$$

- ▶ We use this estimate in Eq.(24) to estimate f

Procedure

- ▶ Compute \hat{f} as follows:

$$\hat{f} = \arg \max_{\tilde{f}} \left(-\rho(0) + 2\Re \left\{ \sum_{m=0}^{kJ-1} \rho(m) e^{-j2\pi\tilde{f}m} \right\} \right) \quad (26)$$

$$\text{where } \rho(m) = \sum_{l=0}^{kJ-1} [\underline{\underline{\mathbf{B}}}]_{l-m,m} r[l] r^*[l-m] \quad (27)$$

$$\text{and } \underline{\underline{\mathbf{B}}} \triangleq \underline{\underline{\mathbf{s}}} (\underline{\underline{\mathbf{s}}}^H \underline{\underline{\mathbf{s}}})^{-1} \underline{\underline{\mathbf{s}}}^H \quad (28)$$

- ▶ Compute $\hat{\underline{\underline{\mathbf{h}}}}$ using the LS estimate on the counter-rotated received samples using $\hat{\underline{\underline{\mathbf{h}}}}(\tilde{f}) = (\underline{\underline{\mathbf{s}}}^H \underline{\underline{\mathbf{s}}})^{-1} \underline{\underline{\mathbf{s}}}^H \underline{\underline{\Gamma}}^H(\tilde{f}) \underline{\underline{\mathbf{r}}}$.

Simulation Results (1/2)

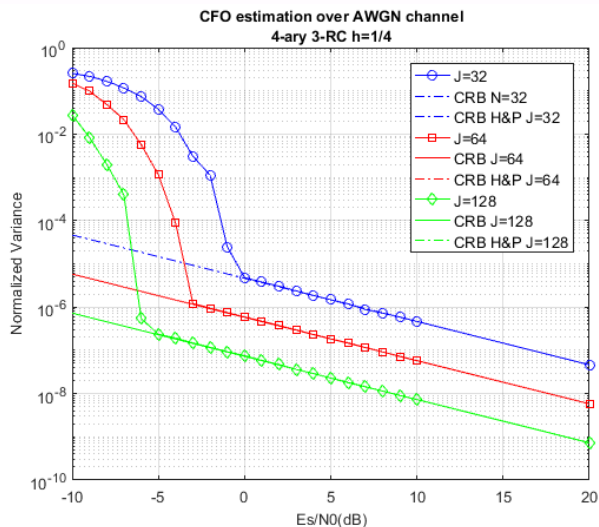


Figure: Carrier Recovery for 4-ary CPM over AWGN channel

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Simulation Results (2/2)

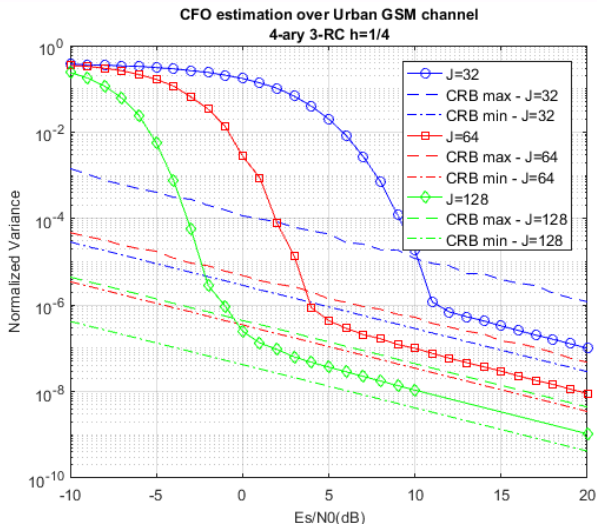


Figure: Carrier Recovery for Quaternary 3-RC h=1/4 over Urban GSM channel

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 - ▶ Parametric Estimation with an *a priori* knowledge on the delays
- ▶ Derivation of a joint ML Channel and CFO Estimator
 - ▶ For both TIV and TV channels
 - ▶ Reaches the CRB (also derived) asymptotically

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- ▶ Preamble design

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- ▶ Receiver Windowing for Band MMSE-FDE for CPM transmissions over doubly-selective channels
- ▶ Preamble design
- ▶ Timing Recovery

- ▶ Non-linear equalization scheme (DFE or Turbo)
- ▶ Receiver Windowing for Band MMSE-FDE for CPM transmissions over doubly-selective channels
- ▶ Preamble design
- ▶ Timing Recovery
- ▶ Optimal BEM model for the aeronautical channel

List of publications

Journal Paper:

- ▶ "A New Exact Low-Complexity MMSE Equalizer for Continuous Phase Modulation", *IEEE Communications Letters*, 2018

International conference papers:

- ▶ "Doubly-Selective Channel Estimation for Continuous Phase Modulation", *IEEE Int. Military Communications Conference (MILCOM)*, Los Angeles (CA), U.S.A, 2018
- ▶ "A Frequency-Domain Band-MMSE Equalizer for Continuous Phase Modulation over Frequency-Selective Time-Varying Channels", *European Signal Processing Conference (EUSIPCO)*, Rome, Italy, 2018
- ▶ "Channel Estimation and Equalization for CPM with application for aeronautical communications via a satellite link", *IEEE Int. Military Communications Conference (MILCOM)*, Baltimore (MD), U.S.A, 2017
- ▶ "Joint Channel and Carrier Frequency Estimation for M -ary CPM over frequency-selective channel using PAM decomposition", *IEEE Int. Conf. Acoust., Speech, and Signal Proc. (ICASSP)*, New Orleans LA, U.S.A, 2017

National conference paper:

- ▶ "Sur l'égalisation fréquentielle des modulations à phase continue", *Colloque GRETSI sur le traitement du Signal*, Juan-les-pins, France, 2017

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MMSE-FDE [TS05] (1/2)

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Based on an orthogonal basis of the signal space $\{f_k(t)\}$

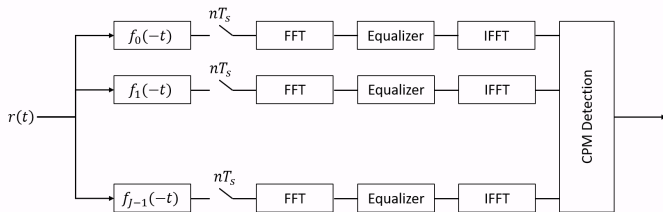


Figure: MMSE-FDE with orthogonal representation from [TS05]

Requires delays multiple of T_s

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MMSE-FDE [TS05] (2/2)

Based on the Laurent Decomposition

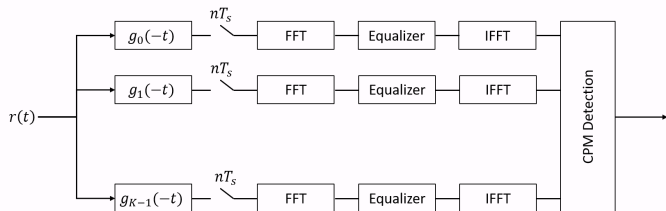


Figure: MMSE-FDE from [TS05]

Does not take into account the auto-correlation of the pseudo-symbols

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Parametric Least Squares Estimation (1/2)

- ▶ directly estimate the attenuations $\{h_l\}_l$ and the delays $\{\tau_l\}_l$ of the different path of the channel
- ▶ the delays are known in this aeronautical context by GPS and geometrical consideration
- ▶ Introduction of the dependency on those delays:

$$\underline{\underline{P}}(\underline{\tau}) = \begin{bmatrix} \Psi(0 - \tau_0) & \dots & \Psi(0 - \tau_{L_c-1}) \\ \Psi(T_e - \tau_0) & \dots & \Psi(T_e - \tau_{L_c-1}) \\ \vdots & \dots & \vdots \\ \Psi(kNT_e - \tau_0) & \dots & \Psi(kNT_e - \tau_{L_c-1}) \end{bmatrix} \quad (29)$$

$$\text{and so } \underline{h} = \underline{\underline{P}}(\underline{\tau})[h_0, h_1, \dots, h_{L_c-1}]^T \quad (30)$$

Parametric Least Squares Estimation (2/2)

- ▶ New system model:

$$\underline{r} = \underline{s}\underline{h} + \underline{w} = \underbrace{\underline{s}\underline{P}(\underline{\tau})}_{=\underline{s}(\underline{\tau})} \underline{a} + \underline{w} \quad (31)$$

$$= \underline{s}(\underline{\tau})\underline{a} + \underline{w} \quad (32)$$

- ▶ LS channel estimation:

$$\hat{\underline{a}} = (\underline{s}(\underline{\tau})^H \underline{s}(\underline{\tau}))^{-1} \underline{s}(\underline{\tau})^H \underline{r} \quad (33)$$

$$\text{and } \hat{\underline{h}} = \underline{P}(\underline{\tau})\hat{\underline{a}} \quad (34)$$

- ▶ lower bound of the more generic case where a joint delays and attenuations estimation
- ▶ lower complexity and better performance

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System Model

- ▶ We assume perfect timing synchronization
- ▶ Unknown parameters:
 - ▶ Propagation Channel
 - ▶ Carrier Frequency Offset
 - ▶ Initial Phase
- ▶ Doubly-selective channel:

$$\underline{r} = \underline{hs} + \underline{w} \quad (35)$$

$$\text{with } \underline{r} = [r[0], r[1], \dots, r[kN - 1]]^T$$

$$\underline{s} = [s[0], s[1], \dots, s[kN - 1]]^T$$

$$\text{and } \underline{w} = [w[0], w[1], \dots, w[kN - 1]]^T$$

with

$$\underline{h} = \begin{bmatrix} h[0, 0] & 0 & \dots & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ h[L - 1, L - 1] & & \ddots & \ddots & \vdots \\ \vdots & \ddots & & \ddots & 0 \\ 0 & \dots & h[kN - 1, L - 1] & \dots & h[kN - 1, 0] \end{bmatrix} \quad (36)$$

Basis Expansion Model (BEM)

- ▶ Complex attenuation of the l^{th} path:

$$\underline{h}_l = [h[0, l], h[1, l], \dots, h[kN - 1, l]]^T \quad (37)$$

$$= \underbrace{[\underline{\zeta}_0, \underline{\zeta}_1, \dots, \underline{\zeta}_{P-1}]}_{\underline{\zeta}} \underbrace{[\eta_{l,0}, \eta_{l,1}, \dots, \eta_{l,P-1}]^T}_{=\underline{\eta}_l} \quad (38)$$

$$= \sum_{p=0}^{P-1} \eta_{l,p} \underline{\zeta}_p \quad (39)$$

- ▶ $\{\underline{\zeta}_p\}$ is a basis of the attenuation's vectors space
- ▶ This basis is deterministic
- ▶ Only have to estimate the $P(L - 1)$ coefficients $\{\eta_{l,p}\}$ ($P \ll kN - 1$)

Matrix-wise representation of the received signal

- ▶ Channel Matrix:

$$\underline{\underline{\mathbf{h}}} = \sum_{l=0}^{L-1} \underline{\underline{\mathbf{z}}}_l \text{diag}(\underline{\mathbf{h}}_l) \quad (40)$$

$$= \sum_l \sum_p \eta_{l,p} \underbrace{\text{diag}(\underline{\zeta}_p) \underline{\underline{\mathbf{z}}}_l}_{=\underline{\underline{\Omega}}_{l,p}} = \sum_l \sum_p \eta_{l,p} \underline{\underline{\Omega}}_{l,p} \quad (41)$$

$$= \underline{\underline{\Omega}}(\underline{\underline{\eta}} \otimes \underline{\underline{I}}_{kN}) \quad (42)$$

- ▶ Received signal:

$$\underline{\mathbf{r}} = \underline{\underline{\Omega}}(\underline{\underline{\eta}} \otimes \underline{\underline{I}}_{kN}) \underline{\mathbf{s}} + \underline{\mathbf{w}} \quad (43)$$

$$= \underline{\underline{\Omega}}(\underline{\underline{I}}_{LP} \otimes \underline{\mathbf{s}}) \underline{\underline{\eta}} + \underline{\mathbf{w}} \quad (44)$$

LS Estimation of the BEM parameters

- ▶ Similar to the TIV case, let $\underline{\underline{s}} \triangleq \underline{\underline{\Omega}}(\underline{\underline{I}}_{LP} \otimes \underline{\underline{s}})$
- ▶ LS channel estimate:

$$\hat{\underline{\underline{\eta}}} = (\underline{\underline{s}}^H \underline{\underline{s}})^{-1} \underline{\underline{s}}^H \underline{\underline{r}} \quad (45)$$

$$\text{and so } \hat{\underline{\underline{h}}} = \underline{\underline{\Omega}}(\hat{\underline{\underline{\eta}}} \otimes \underline{\underline{I}}_{kN}) \quad (46)$$

- ▶ Can be performed on circular block based CPM transmission using UW

Simulation Results (1/3)

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▶ Scenario:

- ▶ TV aeronautical channel by satellite
- ▶ C-band
- ▶ $C/M = 5\text{dB}$
- ▶ Doppler Spread of $0.0183R_s$, then $0.0008R_s$

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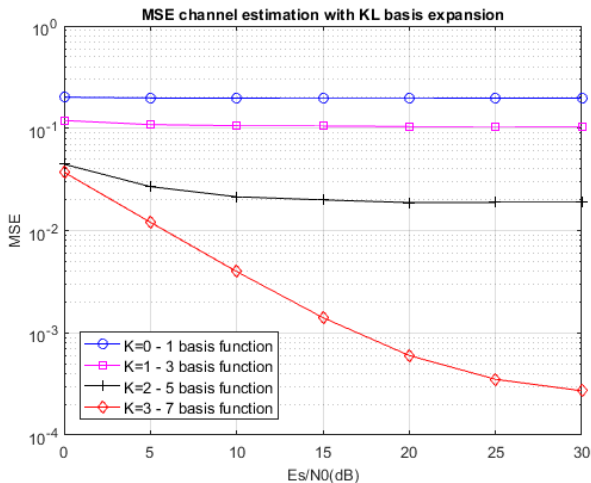


Figure: NMSE over TV channels using KL-BEM

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Simulation Results (3/3)

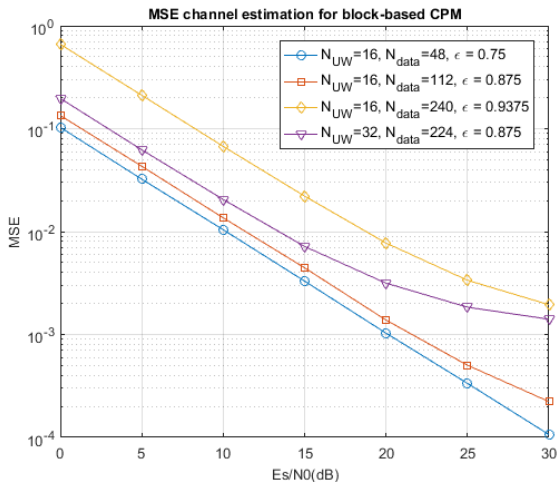


Figure: NMSE over TV channels using KL-BEM for block-based CPM

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Cramér Rao Bound for carrier recovery in case of TIV Channel

- ▶ Sys. Mod.: $\underline{\mathbf{r}} = \underline{\underline{\Gamma}}(f)\underline{\mathbf{s}}\underline{\mathbf{h}} + \underline{\mathbf{w}}$
- ▶ Set of unknown parameters: $u = (\underline{\mathbf{h}}_r, \underline{\mathbf{h}}_j, f)$
- ▶ Fisher Information Matrix:

$$[\underline{\underline{\mathbf{F}}}]_{i,j} = -E \left[\frac{\partial^2 \ln \Delta(\underline{\mathbf{r}}, u)}{\partial u(i) \partial u(j)} \right]$$

- ▶ $\text{CRB}(f) = \frac{\sigma_n^2}{2\underline{\mathbf{y}}^H(\underline{\underline{\mathbf{I}}}_{kJ} - \underline{\underline{\mathbf{B}}})\underline{\mathbf{y}}}$

$$\text{with } \underline{\mathbf{y}} = 2\pi \underline{\underline{\mathbf{M}}}\underline{\mathbf{s}}\underline{\mathbf{h}}$$

$$\text{and } \underline{\underline{\mathbf{M}}} = \text{diag}(0, 1, \dots, kJ - 1)$$

- ▶ AWGN Case:

$$\text{CRB}_{\text{AWGN}}(f) = \frac{\sigma_n^2}{2\underline{\mathbf{y}}^H(\underline{\underline{\mathbf{I}}}_{kJ} - \underline{\underline{\mathbf{B}}})\underline{\mathbf{y}}} \approx \frac{3}{2\pi^2 J^3} (\text{SNR})^{-1}$$

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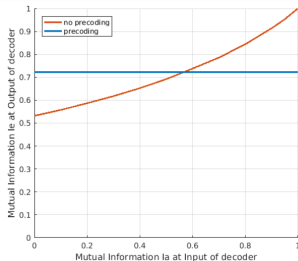
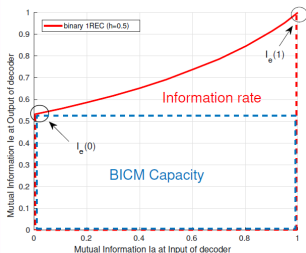
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- ▶ cf Thesis "Nouvelle forme d'onde et récepteur avancé pour la télémétrie des futurs lanceurs", by C.-U. Piat-Durozoi



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